

18. The method of claim 17, further comprising:  
 acquiring three-dimensional point cloud data descriptive  
 of at least a portion of the actual object; and  
 wherein the determining the actual orientation is based at  
 least in part on the three-dimensional point cloud data. 5

19. The method of claim 17, wherein:  
 the actual object comprises a human; and  
 the item is representative of one of:  
     a wristwatch;  
     a pair of eyeglasses; or 10  
     a piece of furniture.

20. The method of claim 15, further comprising:  
 determining movement of the actual object relative to the  
 device;  
 modifying a position of the actual object within the 15  
 representation based on the movement of the actual  
 object relative to the device;  
 determining a moved orientation of the actual object;  
 in response to the moved orientation, determining a 20  
 corresponding moved orientation of the item that  
 causes the item to appear engaged to the actual object;  
 modifying a position of the item within the representation  
 based on the movement of the actual object by posi-  
 tioning the item in the corresponding moved orienta-  
 tion and engaged to the actual object; and 25  
 modifying a position of the fourth image within the  
 representation based on the modifying of the position  
 of the item within the representation.

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